



# Product information

## PJ-57en

### BMT Disk-Type Tool Turret

Series 434.0xx

**revision 2024/05/31**

#### **Attention**

High pressure turret exceeding 50bar: For safety purpose, it is required to use high pressure tool holders which match specifications of turret.

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## BMT Disk-Type Tool Turret

### Series 434.0xx

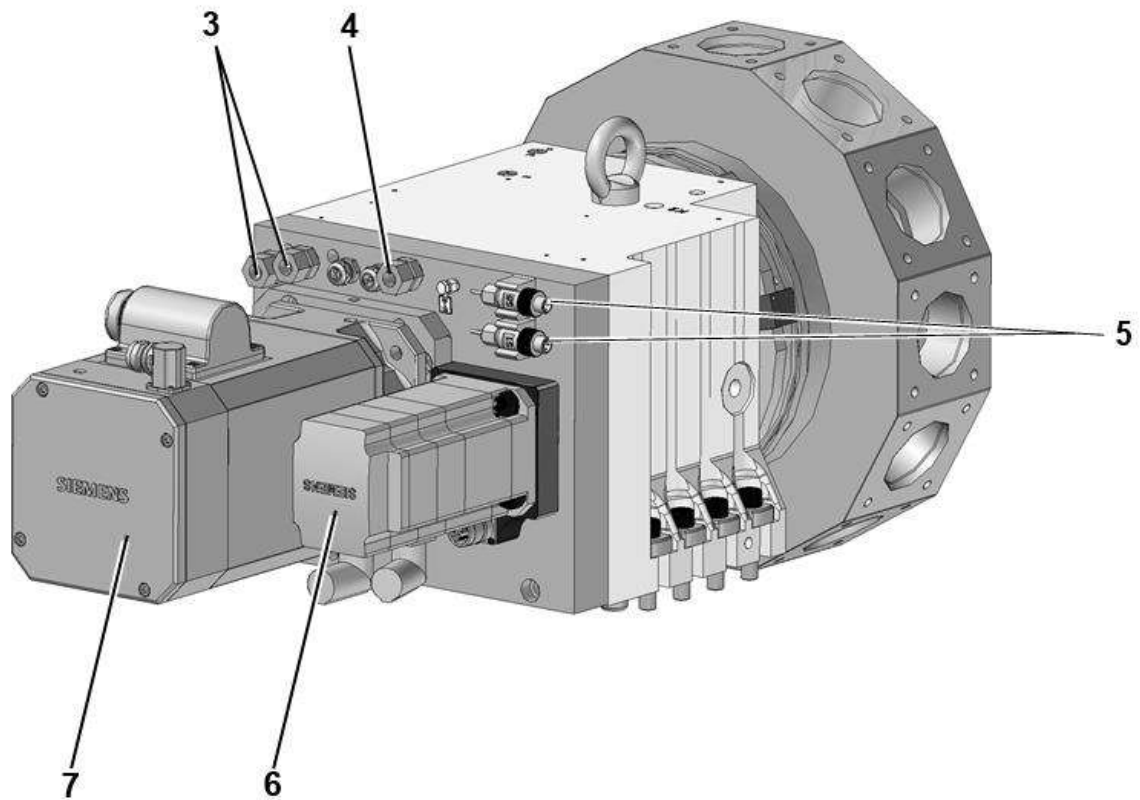
#### Description

These turrets are suitable for use on turning machines for forward and reverse machining. They are equipped with all of the features and functions of modern high performance tool turrets. They are suitable for series manufacture due to their robust design and short switching times.

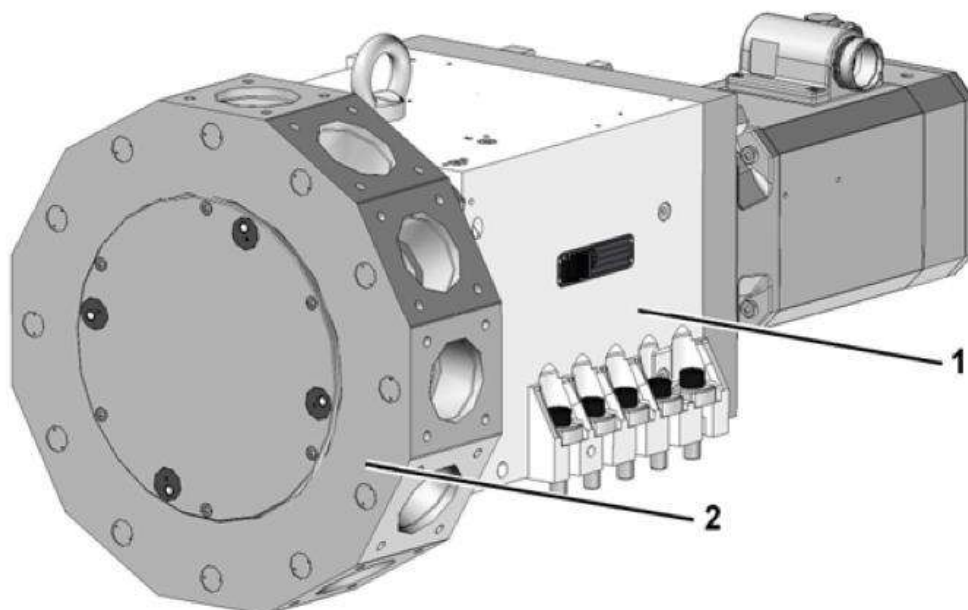
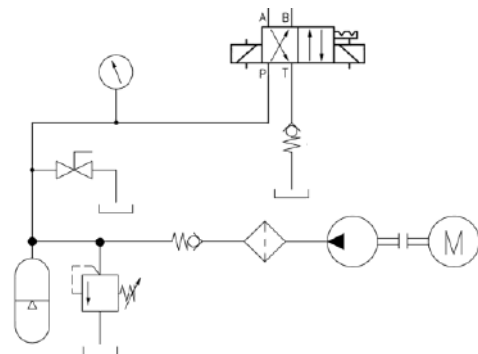
#### Features

- Drive with controllable electric motor for very fast bidirectional swivel use of:
  - GPM drive unit EK 700 with motor and converter
  - GPM drive with rotary encoder activation and customary control
  - or customary servo motors
- Heavy loads of stability due to high locking forces
- Hydraulic locking with special triple generating crown gear (pat.)
- Not affected by collisions due to:
  - ↔ [Low kinetic energy of the drive, and](#)
  - ↔ [Fastening snap-ring groove for the tool disk](#)
- Directly controllable with machine controller (not apply to GPM drive unit EK 700)
- Can be installed in any position
- For all market BMT - interfaces (BMT45 / 55 / 65 / 75 / 85 a.o.)
- Options:
  - BMT turret Premier Series : Performance upgrade for long term operation
  - High pressure coolant solution
  - Others

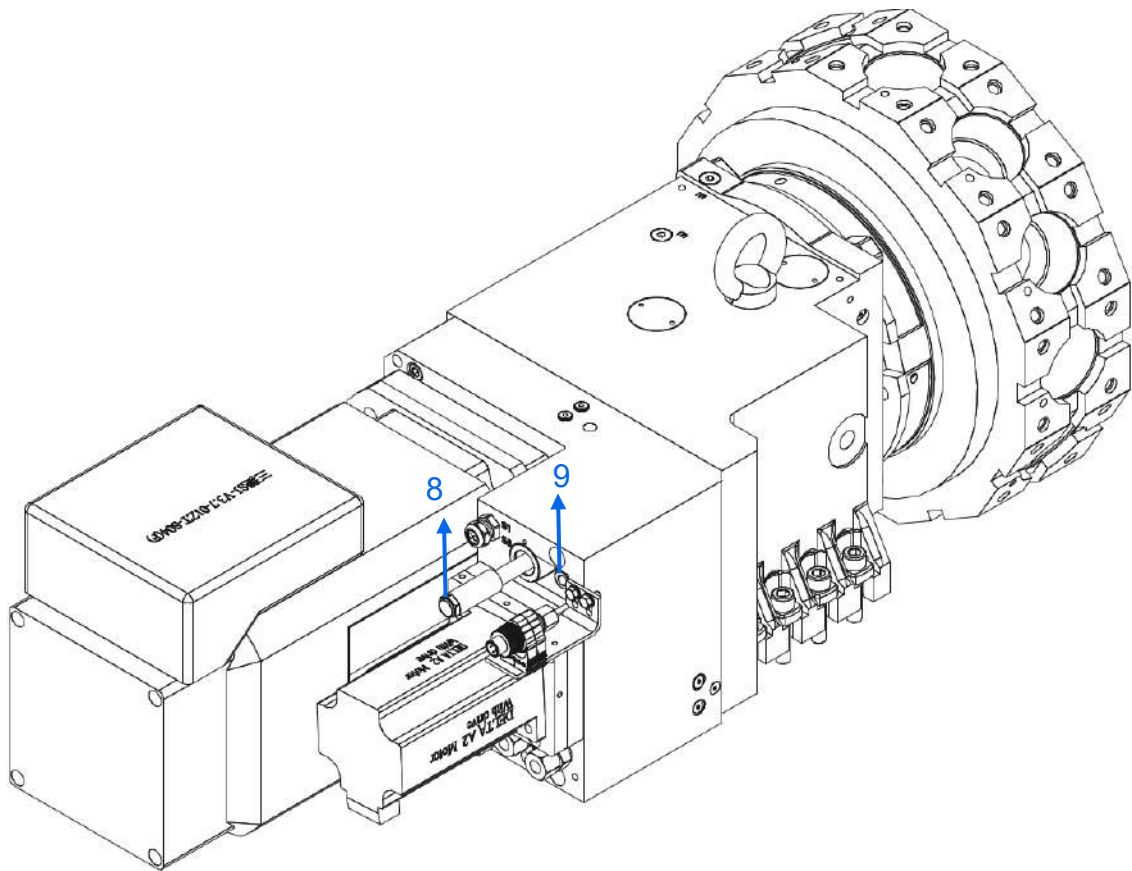
Standard appearance :



- 1 Turret housing
- 2 Tool disk
- 3 Connection – hydraulic locking control
- 4 Connection – cooling coolant
- 5 Connection - Electric
- 6 Indexing motor
- 7 Tool drive motor



Premier Series appearance (Option) :



- 8. Air cooling Out (option)
- 9. Air cooling In (option)

## Technical Data

<b>Series</b>	
<b>BMT Disk-type tool turret 434.0xx</b>	
<b>Number of switching positions</b>	
Admissible tangential load (turret locked) <sup>1)</sup>	kNm
Admissible mass moment of inertia of tools <sup>1)2)</sup> with tool disk and holder	Standard load stage High load stage
	kgm <sup>2</sup> kgm <sup>2</sup>
Admissible out of balance (load moment ) due to tooling	Nm
Gear ratio swivel drive <sup>3)</sup>	i
<b>Switching times<sup>3)</sup></b>	
Rotate tool disk: <sup>5)</sup>	
• incl. acceleration and braking per partial step	Standard load stage High load stage
	s s
• without acceleration and braking per additional partial step	
	s
Turret unlock/lock-hydraulic	s
Adm. switching frequency <sup>3)</sup> (median switching angle $\varphi_m = 90^\circ$ )	
<b>Operating pressure</b>	
Hydraulic $\pm 10\%$	bar
Cooling lubricant	
• Standard	bar
• Medium pressure value	bar
• High-pressure cooling lubricant device	bar
<b>Fluid absorption volume</b>	
Turret unlock/lock	cm <sup>3</sup>
<b>Mass</b>	
Turret (incl. drive motor)	kg
Tool disk and tooling (max) <sup>4)</sup>	kg
<b>Adm. ambient temperature</b>	
	°C

Size											
16			20			25			32		
8	12	16	8	12	16	8	12	16	8	12	16
1.8			3.6			7.2			12.5		
1.8			3.2			8			25		
2.5			5.0			12			40		
32			63			125			200		
54			72			90			216		
0.16			0.16			0.21			0.27		
0.15			0.19			0.25			0.31		
0.07			0.09			0.11			0.27		
0.12			0.13			02			0.5		
20			16			12			10		
50			50			50			50		
5-25(Filtering $\leq 100\mu\text{m}$ ) <sup>5)</sup> 5-50Filtering $\leq 500\mu\text{m}$ ) <sup>5)</sup> 150(Filtering $\leq 25\mu\text{m}$ ) <sup>5)</sup>											
30			45			65			114		
100			155			270			570		
80			160			250			400		
10~40											

- 1) Higher values on request
- 2) Switching times  
Conditions:
  - Fluid supply sufficiently large
  - Turret up to operating temperature
  - Without controller-related non-productive time
  - Switching times valid for high dynamic motor (e.g. 1FK7043)
- 3) The swivel times are determined with an average load. Further details on request.
- 4) High load for special tools on request
- 5) Ensure compliance with the required fineness for the tools used. For example drive tool with internal cooling lubricant supply.

Recommended indexing motors  degree of protection to IP 67	J	Adm. driving	swiveling times for 30°-step without acceleration and braking			
	kgm <sup>2</sup>	rpm	s			
			Size of turret			
			16	20	25	32
EK600 with encoder <sup>1)</sup>	0.0003	4500	0.06	0.08	0.10	0.24
Siemens 1FK7043 HD	0.0001	6000	0.05	0.06	0.08	0.18
Siemens 1FK7042	0.0003	4500	0.06	0.08	0.10	0.24
Fanuc $\alpha$ 2/5000 / $\beta$ 2/5000	0.0003	4500	0.06	0.08	0.10	0.24
Delta A2 (EK700)	0.0003	4000	0.07	0.09	0.11	0.27

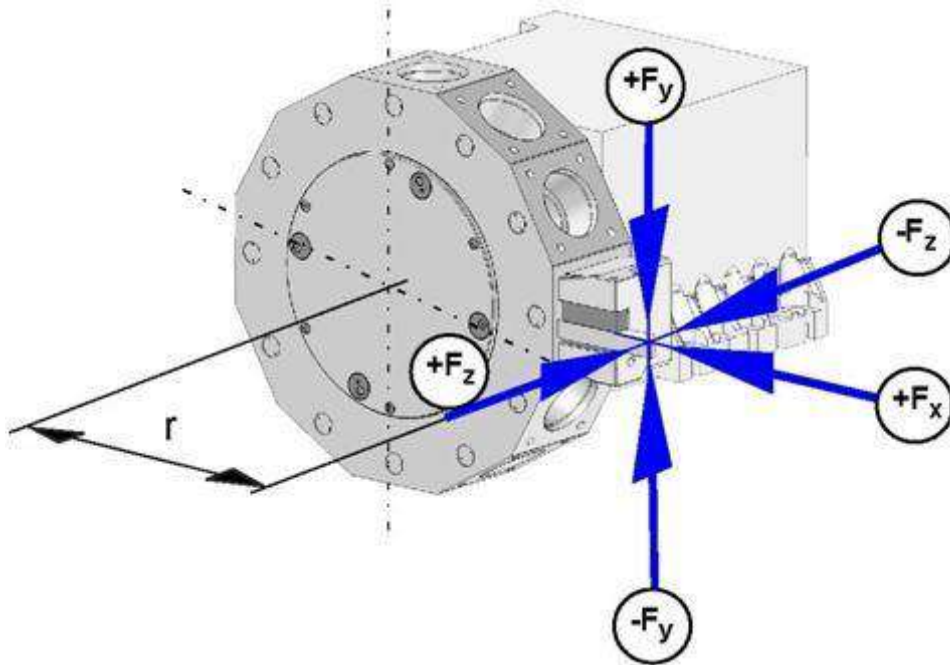
<sup>1)</sup> controlled via machine control system



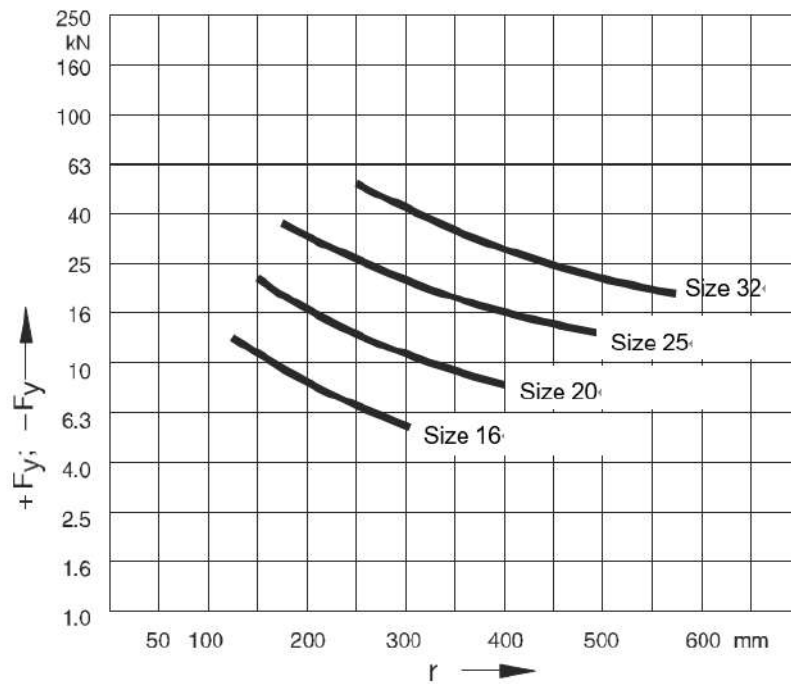
## Admissible Loads

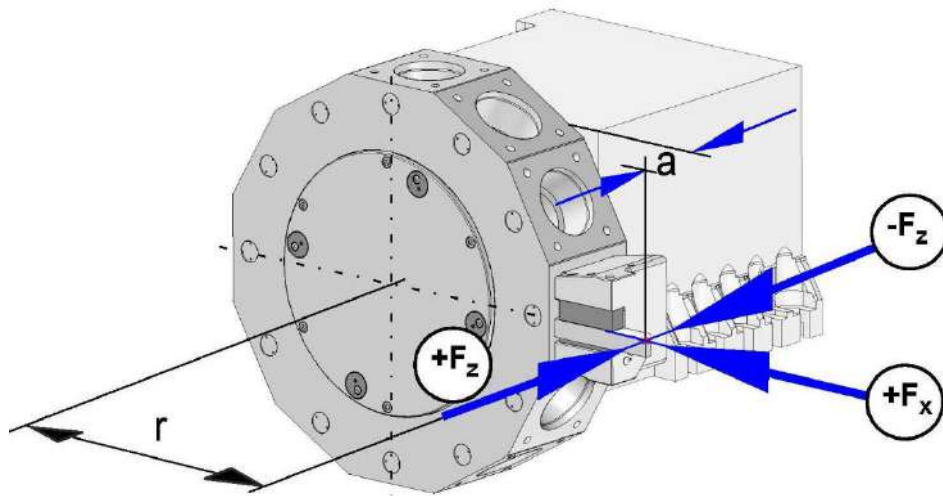
### Note

- The diagrams refer to static loads.
- In case of impact load (interrupted cutting), significantly lower values must be reckoned with.



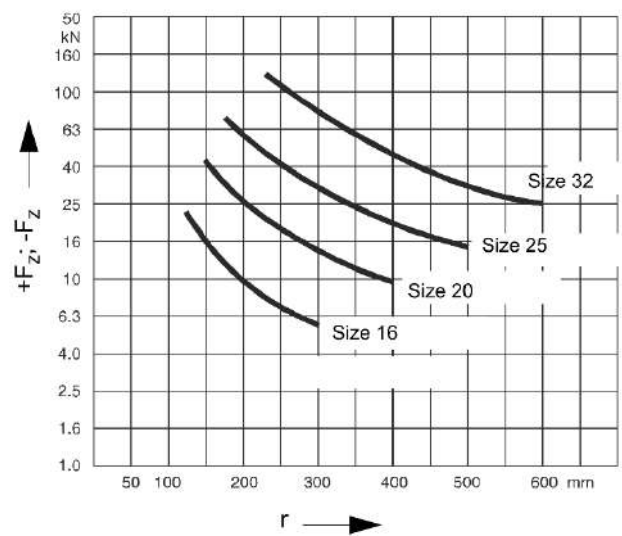
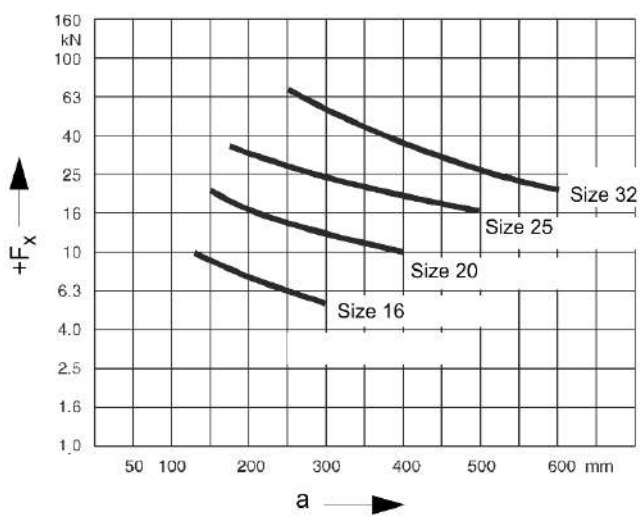
Force  $\pm F_y$   
Tangential loading





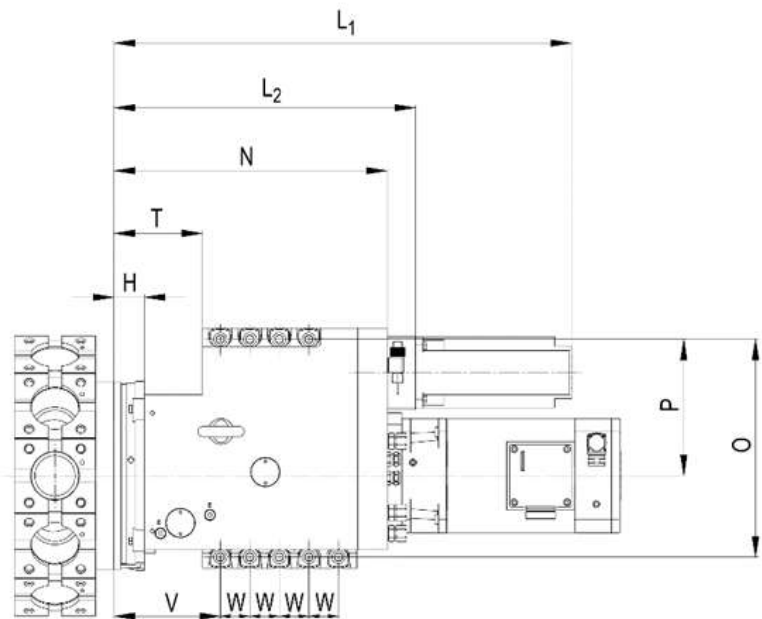
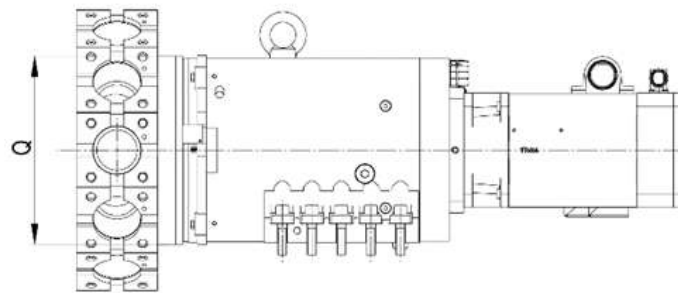
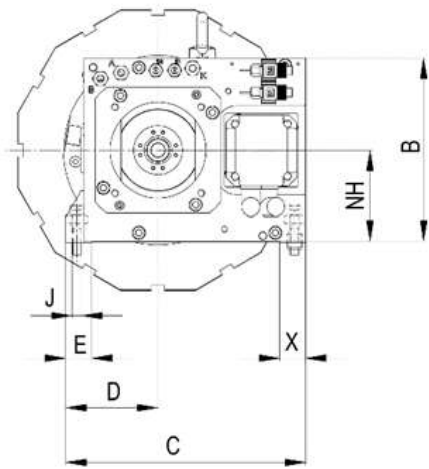
Force +Fx  
 Shunt loading  
 leading edge is the basis for dimension a

Force + Fz  
 longitudinal loading



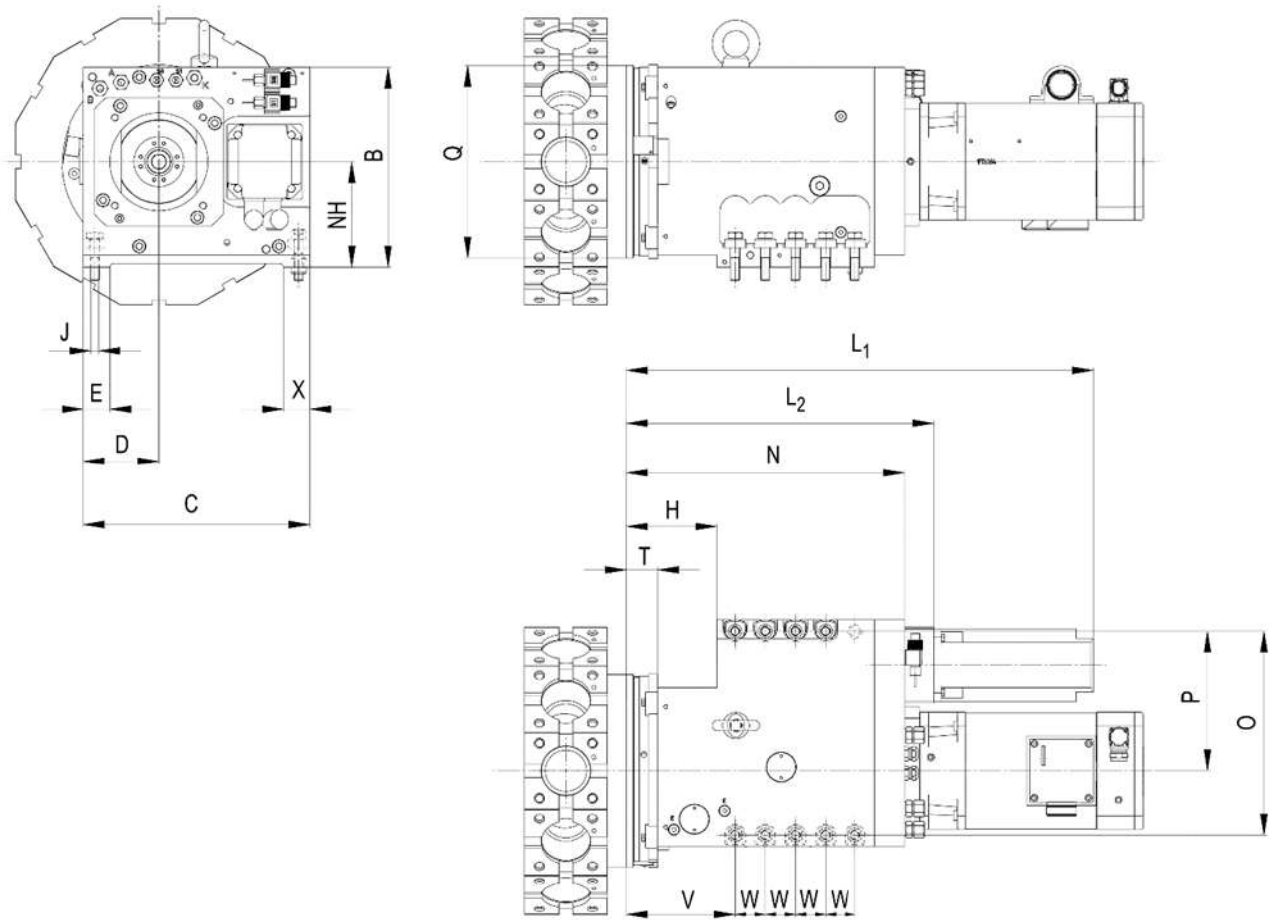
## Dimension

### L-shape (NH Standard 1)



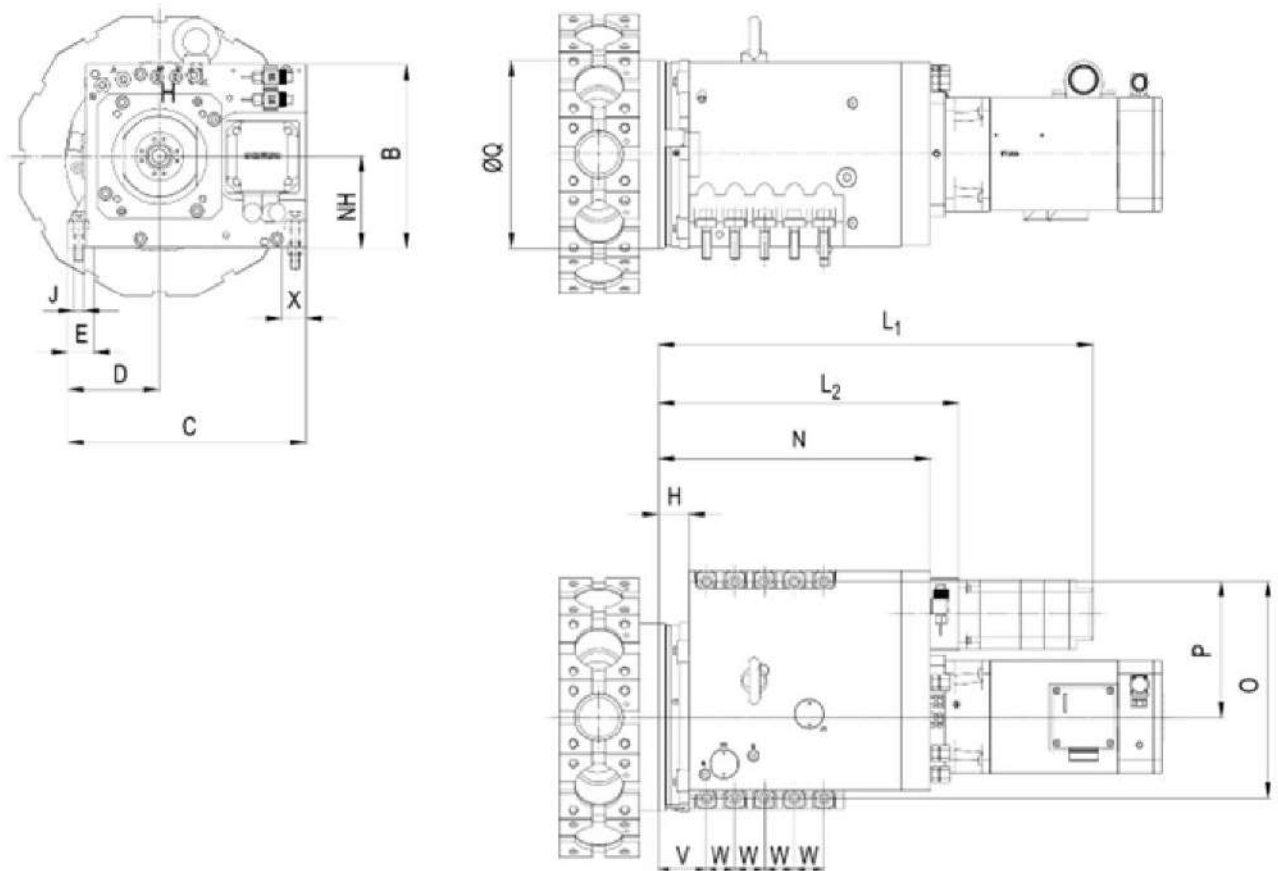
Series		Size			
<b>434.0XX (L shape-NH Standard 1)</b>		16	20	25	32
NH		100	125	150	
B		200	250	300	
C		284	325	406	
D		102	125	158	
E		26	35	45	
H		40	41	52	
J		M10	M12	M16	
L					
GPM drive 1.8.150.573	L <sub>1</sub>	454	474	520	
Delta motor with drive	L <sub>1</sub>	375	395	441	
Siemens 1FK70 43/42	L <sub>2</sub>	374	394	440	
Fanuc $\alpha 2/\beta 2$	L <sub>2</sub>	259	379	425	
N		234	370	412	
O		240	295	370	
P		150	185	230	
øQ		160	255	318	
T		105	120	150	
V		127	144	176	
W		34	40	42	
X		34	35	45	

**L-shape (NH standard 2)**



Series		Size			
<b>434.0XX (L shape-NH standard 2)</b>		16	20	25	32
NH			140	180	
B			265	330	
C			300	373	
D			100	125	
E			35	45	
H			41	52	
J			M12	M16	
L					
GPM drive 1.8.150.573	L <sub>1</sub>		474	520	
Delta motor with drive	L <sub>1</sub>		395	441	
Siemens 1FK70 43/42	L <sub>2</sub>		394	425	
Fanuc $\alpha 2/\beta 2$	L <sub>2</sub>		379	425	
N			370	412	
O			270	337	
P			185	230	
øQ			255	318	
T			120	150	
V			144	176	
W			40	42	
X			35	45	

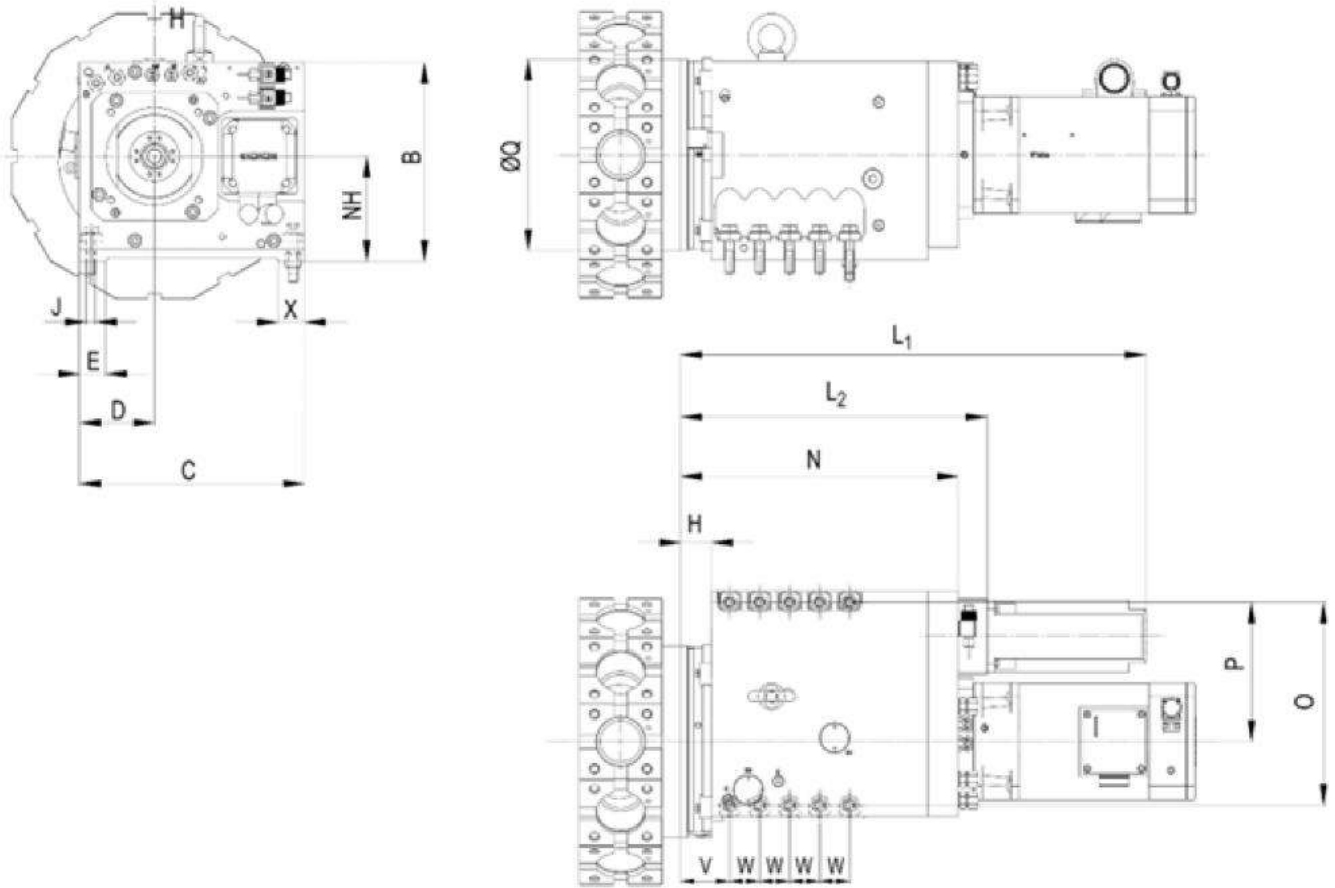
**Block shape (reinforced version / NH standard 1)**



Series		Size			
<b>434.0XX (reinforced version/ NH standard 1))</b>		16	20	25	32
NH		100	125	150	200
B		200	250	300	400
C		284	325	406	520
D		102	125	158	198
E		30	35	45	48
H		40	41	52	62
J		M10	M12	M16	M20
L					
GPM drive 1.8.150.573	L <sub>1</sub>	454	474	520	666
Delta motor with drive	L <sub>1</sub>	545	516	576	722
Siemens 1FK70 43/42	L <sub>2</sub>	438	409	440	586
Fanuc $\alpha 2/\beta 2$	L <sub>2</sub>	123	395	425	571
N		340	370	412	528
O		240	295	370	476
P		150	185	230	300
øQ		160	255	318	396
V		62	65	78	96
W		34	40	42	52
X		50	35	45	48



Block shape (reinforced version / NH standard 2)

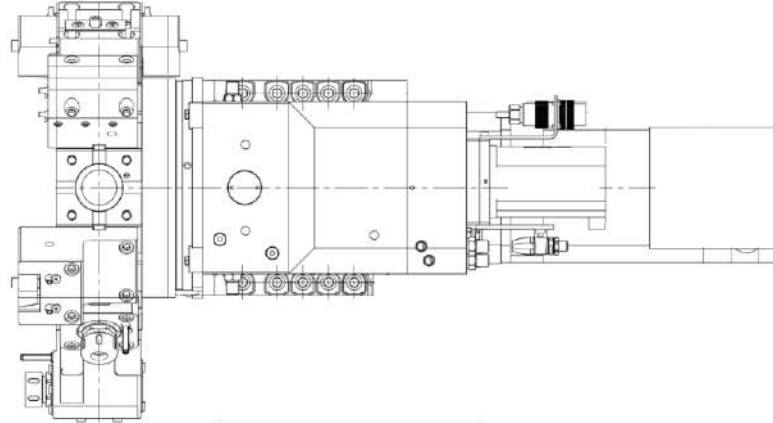


Series		Size			
<b>434.0XX (Block shape reinforced version / NH standard 2)</b>		16	20	25	32
NH			140	180	
B			265	330	
C			300	373	
D			100	125	
E			35	45	
H			41	52	
J			M12	M16	
L					
GPM drive 1.8.150.573	L <sub>1</sub>		474	520	
Delta motor with drive	L <sub>1</sub>		516	576	
Siemens 1FK70 43/42	L <sub>2</sub>		409	440	
Fanuc $\alpha 2/\beta 2$	L <sub>2</sub>		394	425	
N			370	412	
O			295	370	
P			185	230	
øQ			255	318	
V			65	78	
W			40	42	
X			35	45	

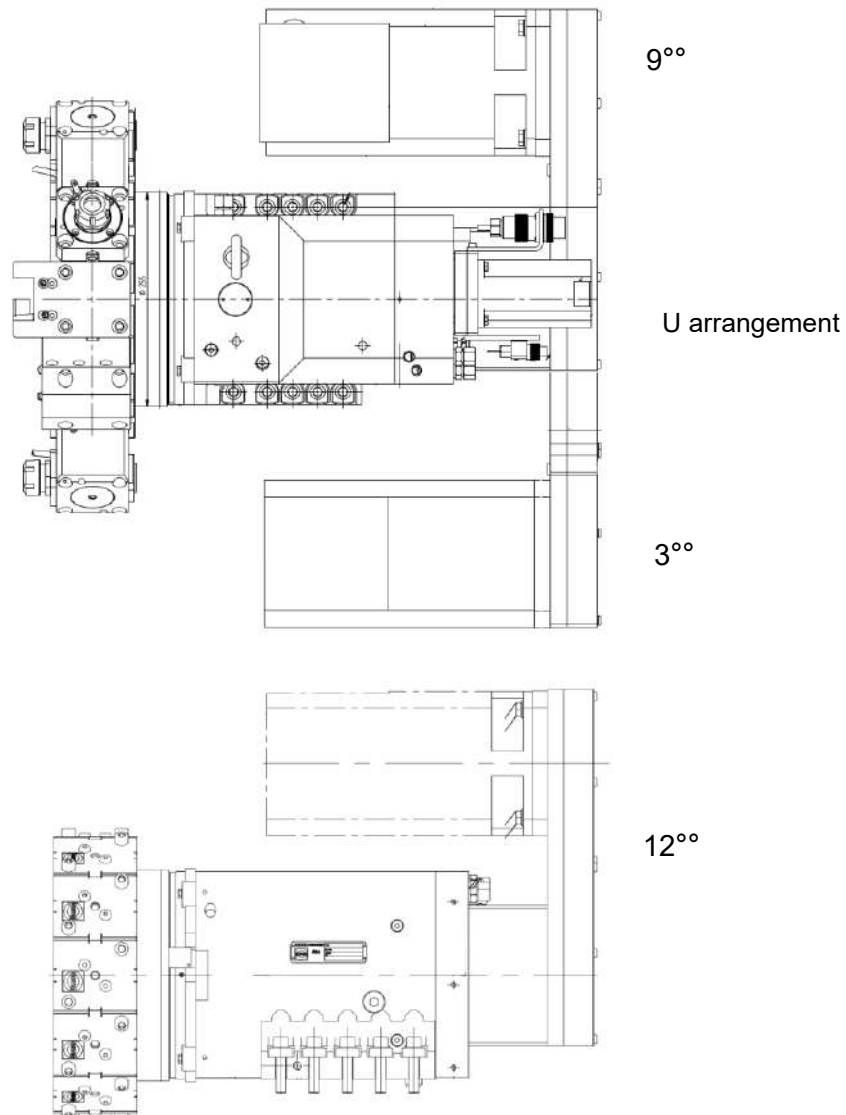
## Motor Arrangement

The tool drive motor can be installed directly on the turret or with a belt drive, depending on the application specifications.

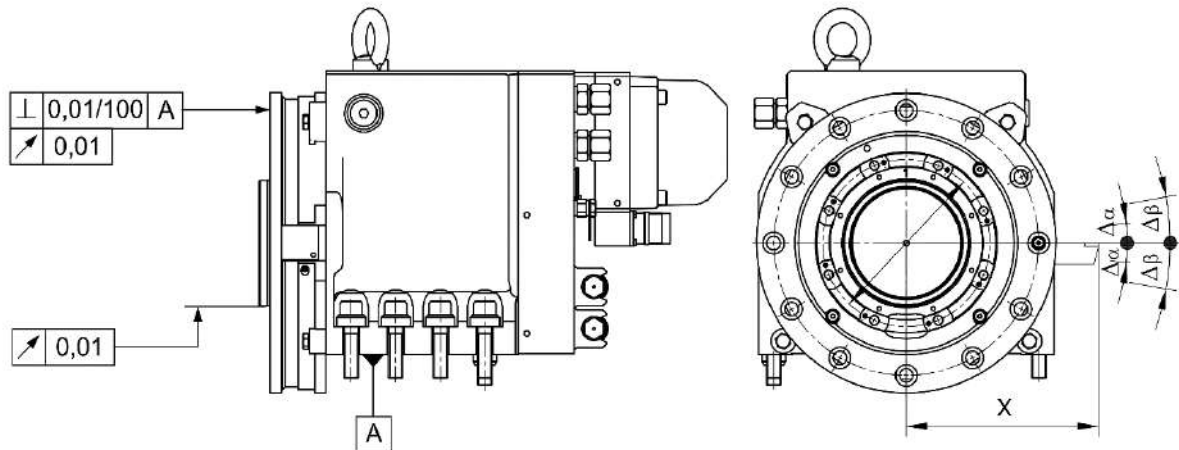
Motor – arrangement – direct-



Motor – arrangement with deflection



## Precision



Repeating accuracy

(Multiple move to a switching position from the same direction)

$$\Delta\alpha = \pm 1.6'' \equiv \pm 0.8 \times \frac{X[\text{mm}]}{100[\text{mm}]} [\mu\text{m}]$$

Indexing precision

(Multiple move to a switching position from the same direction)

$$\Delta\beta = \pm 4'' \equiv \pm 2 \times \frac{X[\text{mm}]}{100[\text{mm}]} [\mu\text{m}]$$

## Performance Data for the Tool Coupling - Standard

The gearbox is designed for the performance data indicated below for the tool coupling.

The actually available performance data depend on the drive motor for tool drive (see below).

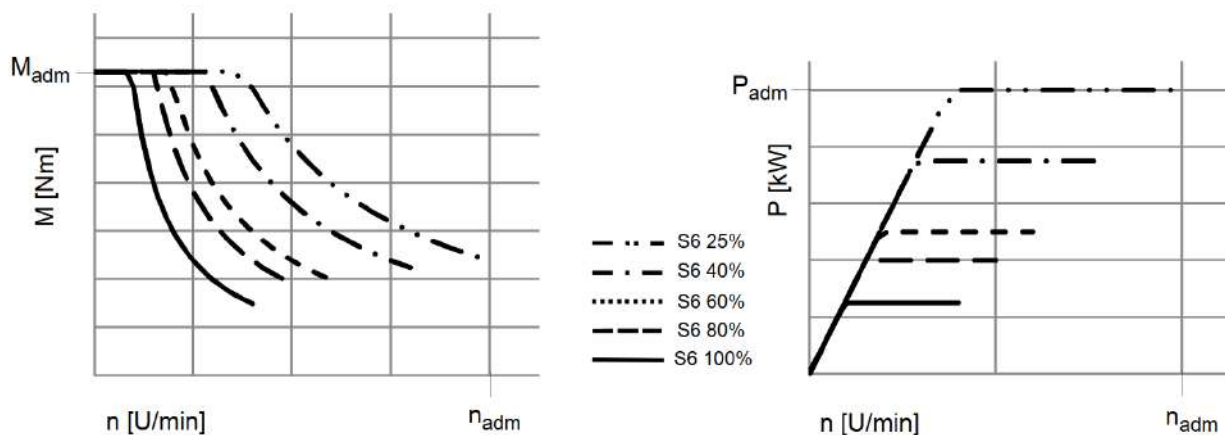
Series	Size			
<b>434.0xx</b>	<b>16</b>	<b>20</b>	<b>25</b>	<b>32</b>
<b>Performance data</b>				
Adm. drive rating <sup>1)</sup> $P_{adm}$ kW	8	10	12.5	16
Adm. torque <sup>2)</sup> $M_{adm}$ Nm	32	63	100	180
Adm. rpm <sup>1)3)</sup> $n_{adm}$ min <sup>-1</sup>	6000	6000	4000	4000
ratio $i=n_1/n_2$	1.0	1.0	1.0	1.0
<b>Recommended motors for tool drive</b>				
Siemens Servo motor				
Type 1FT6..	..84-1AK	..086-1AH	..105-8AF	..108-8AF
Fanuc servo motor $\alpha$	12/6000 is	22/4000 is	40/4000 is	50/3000
Fanuc spindle motor $\alpha$	2	3	6	15 HVi

- 1) The values are reference values for short-term operation. Higher rpm generate more heat and noise.
- 2) Torque limitation at motor converter required! The torque values apply to smooth-machining (such as thread drilling).  
In the case of machining with severe shock loads (e.g. face milling and similar operations) it is necessary to reduce the motor drive torque by 50% or more.
- 3) Higher rpm or long time operation, please go to next page : 434.0xx Premier Series

## Admissible duty cycle (DC)

Tool Drive

Performance Diagram



See Appendix Performance data for tool drive

## Performance Data for the Tool Coupling – Premier Series (Option)

The gearbox is designed for the performance data indicated below for the tool coupling.

The actually available performance data depend on the drive motor for tool drive (see below).

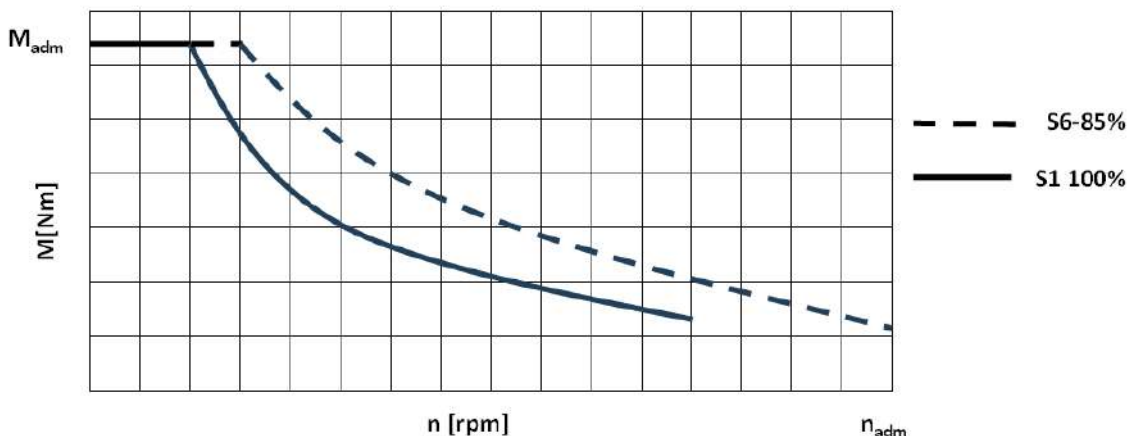
Series		Size		
<b>434.0xx Premier Series</b>		<b>16</b>	<b>20</b>	<b>25</b>
<b>Performance data</b>				
Adm. drive rating <sup>1)</sup>	$P_{adm}$ kW	8	10	12.5
Adm. torque	$M_{adm}$ Nm	32	63	100
Adm. rpm <sup>1)</sup>	$n_{adm}$ min <sup>-1</sup>	8000	8000	6000
ratio $i=n_1/n_2$		1.0	1.0	1.0
<b>Recommended motors for tool drive</b>				
Siemens Servo motor 1FT6..				
		..84-1AK	..086 – 1AH	..105-8AF
Fanuc servo motor $\alpha$		12/6000 is	22/4000 is	40/4000 is
Fanuc spindle motor $\alpha$		2	3	6

- 1) Torque limitation at motor converter required! The torque values apply to smooth-machining (such as thread drilling).  
In the case of machining with severe shock loads  
(e.g. face milling and similar operations) it is necessary to reduce the motor drive torque by 50% or more.

## Admissible duty cycle (DC) – Premier Series(Option)

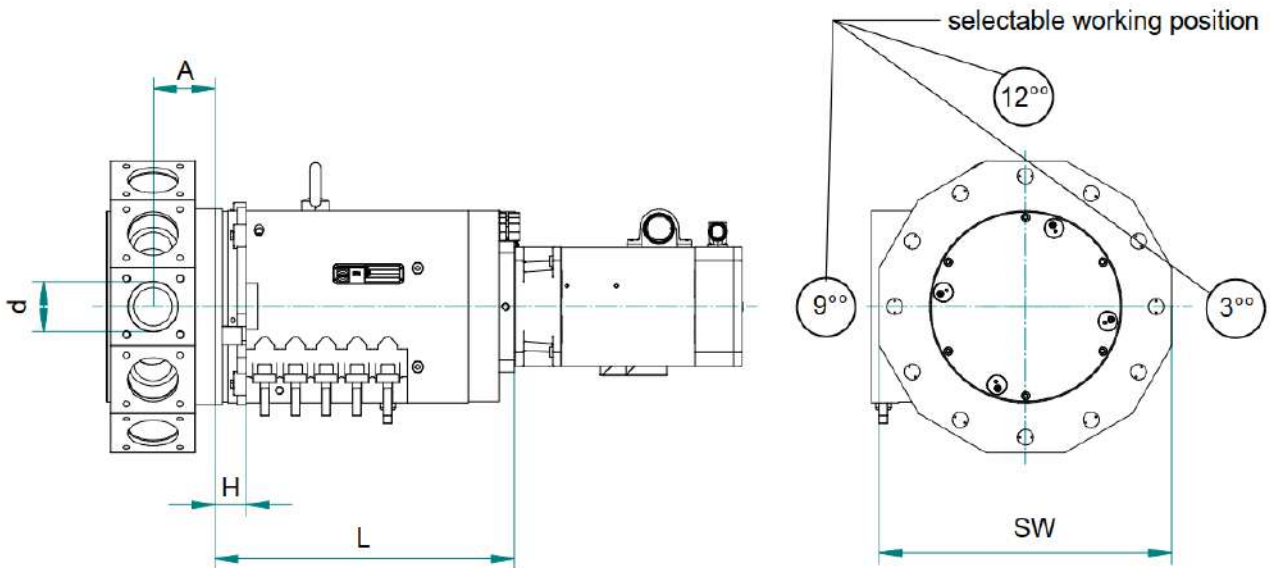
Tool Drive

Performance Diagram



See Appendix Performance data for more detail – page 30

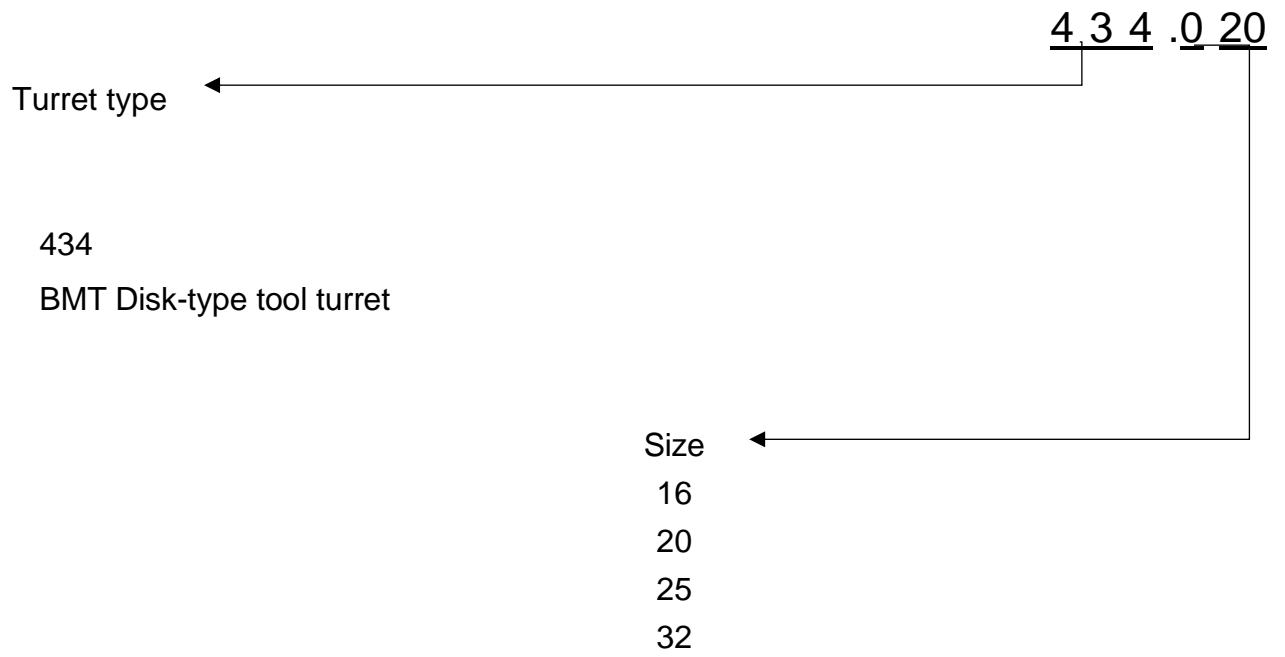
## Dimensions



Series		Size			
<b>434.0xx</b>		<b>16</b>	<b>20</b>	<b>25</b>	<b>32</b>
Tool Coupling DIN 1809 <sup>1)</sup>		BMT 55	BMT 65	BMT 75	BMT 85
Distance	A	70	80	100	120
	H	40	41	52	62
	d	55	65	75	85
SW – standard		330	380	430	530/720
<b>Motors for tool drive</b>					
Siemens Servo motor		1FT084	..086 - 1AH	..105 - 8AF	..108 - 8AF
L		-	390	452	-
Fanuc servo motor $\alpha$		12/6000 is	22/4000 is	40/4000 is	50/3000 is
L		-	-	-	-
Fanuc spindle motor $\alpha$		$\alpha 2$	$\alpha 3$	$\alpha 6$	15 HVi
L		-	-	-	-






1) Other interfaces on request

## Type Key





## Order Details

	Service GPM CO., LTD No. 368, Sec. 4, Huan Zhong Rd., Nan tun District, Taichung City, Taiwan
	+886-4-23805836
	+886-4-23805832
	www.GPMcnc.com
	info@gpmcnc.com

Company: \_\_\_\_\_

Street: \_\_\_\_\_

Postal Code: \_\_\_\_\_


City: \_\_\_\_\_

Name: \_\_\_\_\_

Phone: \_\_\_\_\_

Fax: \_\_\_\_\_

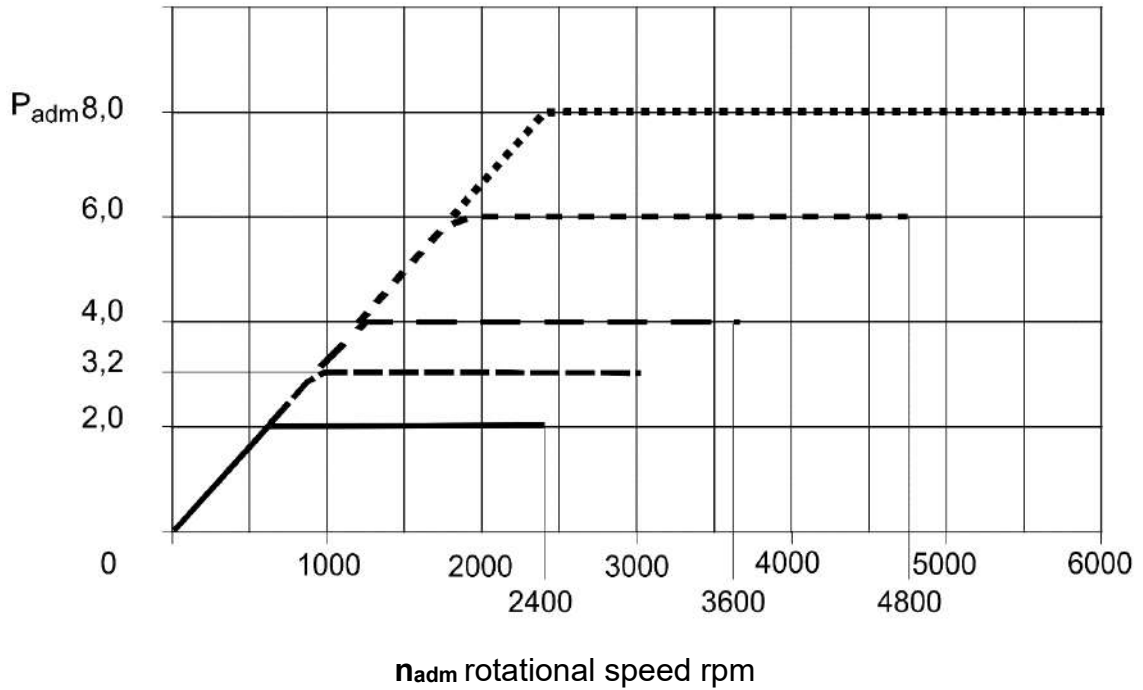
E-Mail: \_\_\_\_\_

Disk-type tool turret 434.0xx		
Ordering informations	Possible configurations	Your selection
<b>Basis turret</b>  Housing shape  Size  Number of switching positions  Motor for indexing drive  Installation position	L / Block (NH 1/2)  20 / 25  8 / 12 / 16  Delta/ Siemens / Fanuc / ...	
<b>Radial tool drive</b>  Working position  Tool disc  Tool system  Motor for tool drive	3° / 9° / 12°  SW  BMT 45 / 55 / 65 / 75 / 85  s. page 20	
<b>Option</b>		
Coolant pressure	25bar/70bar/others	
Premier series function	Long time operation	
<b>Special requirements:</b> 		

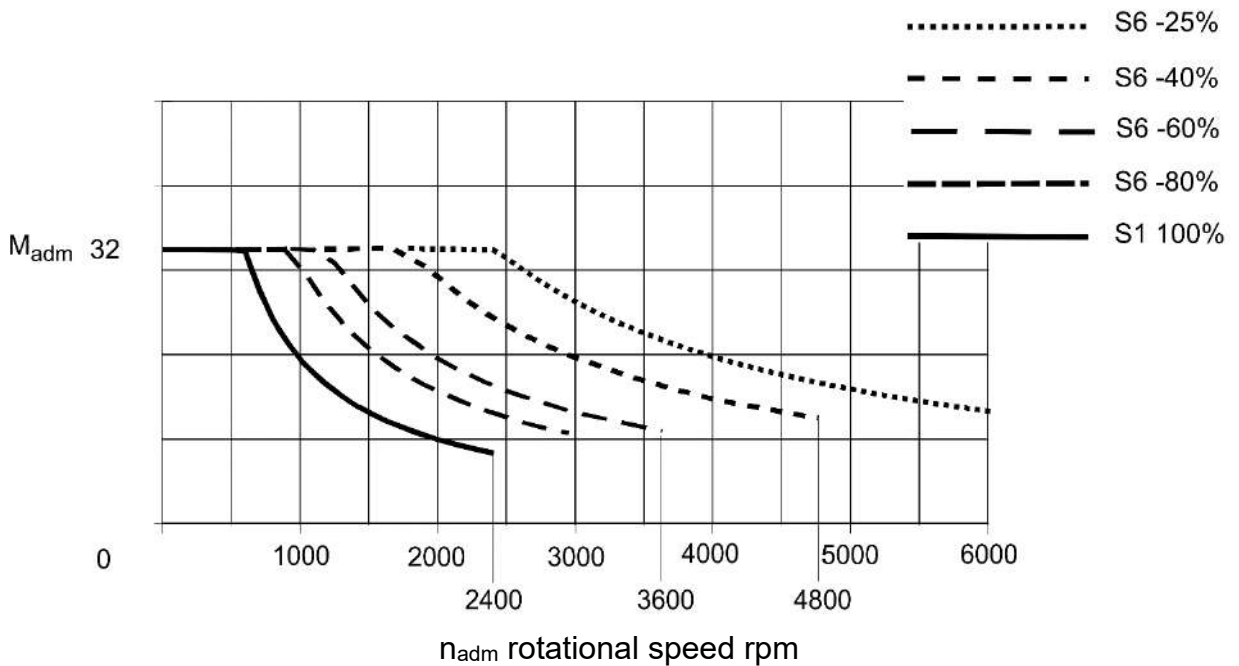
# Appendix

<b>Technical Data</b>	<b>Performance Data Tool Drive (Grease lubricated)</b>	<b>4xx.x16-TI02-zh</b>
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## Power [kW]



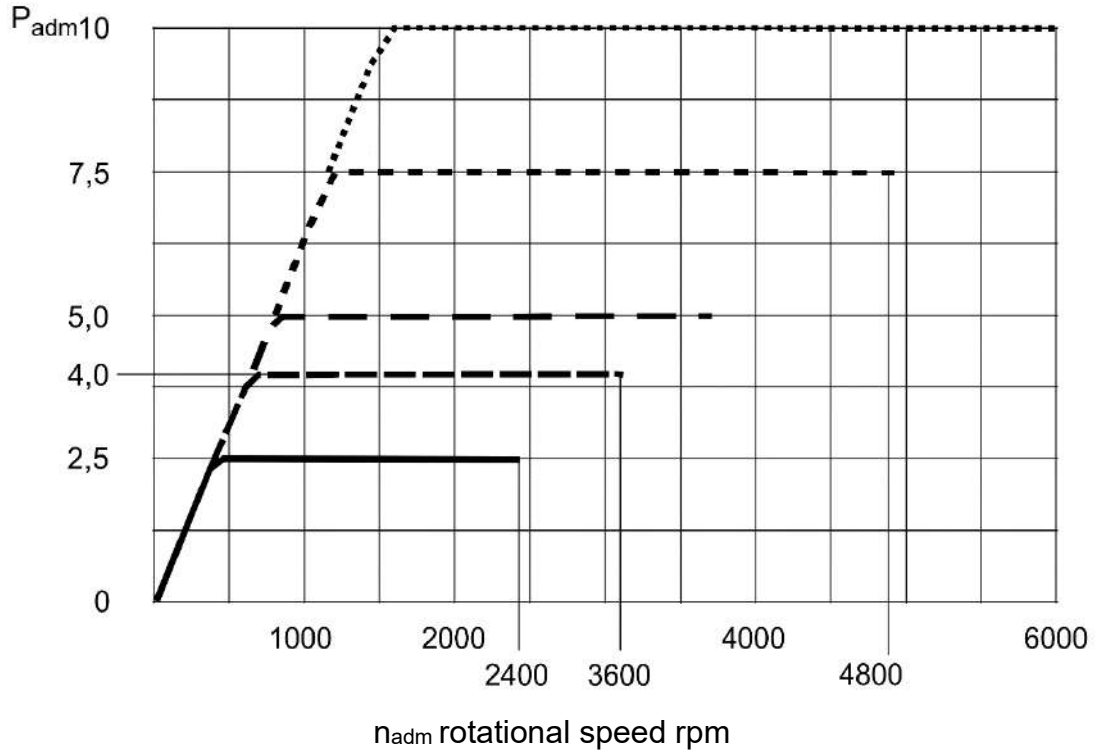
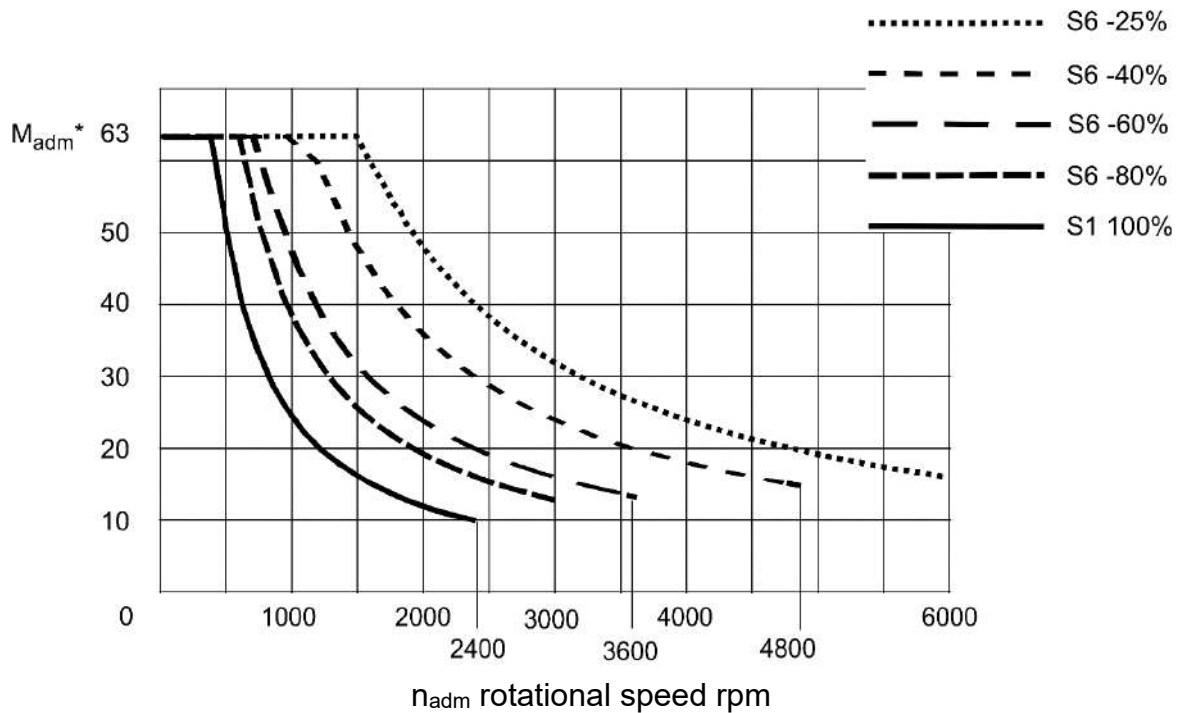
## Torque [Nm]



The data for duty cycle are valid for 10 min.

technical changes reserved.

<b>Technical Data</b>	<b>Performance Data Tool Drive (Grease lubricated)</b>	<b>4xx.x20-TI02-zh</b>
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**Power [kW]**

**Torque [Nm]**


The data for duty cycle are valid for 10 min.

technical changes reserved

<b>Technical Data</b>	<b>Performance Data Tool Drive (Grease lubricated)</b>	<b>4xx.x20-TI02-zh</b>
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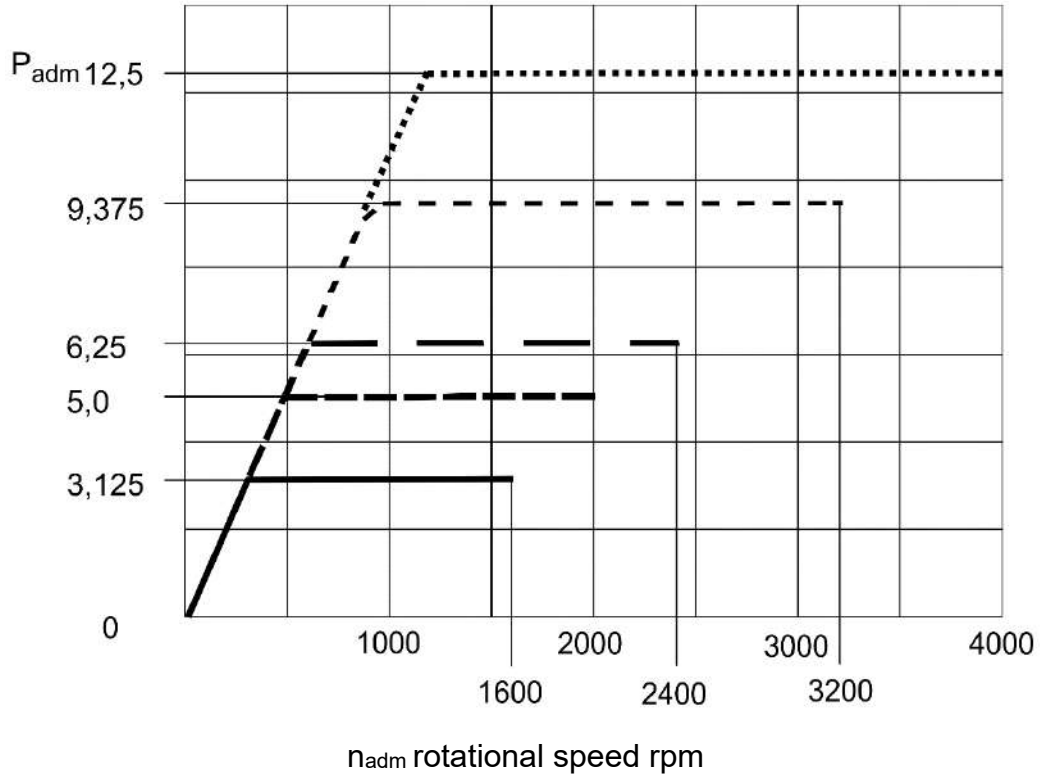
Tool Holder	$M_{adm}$ [Nm]
BMT45	20
BMT55	32

**Technical Data**

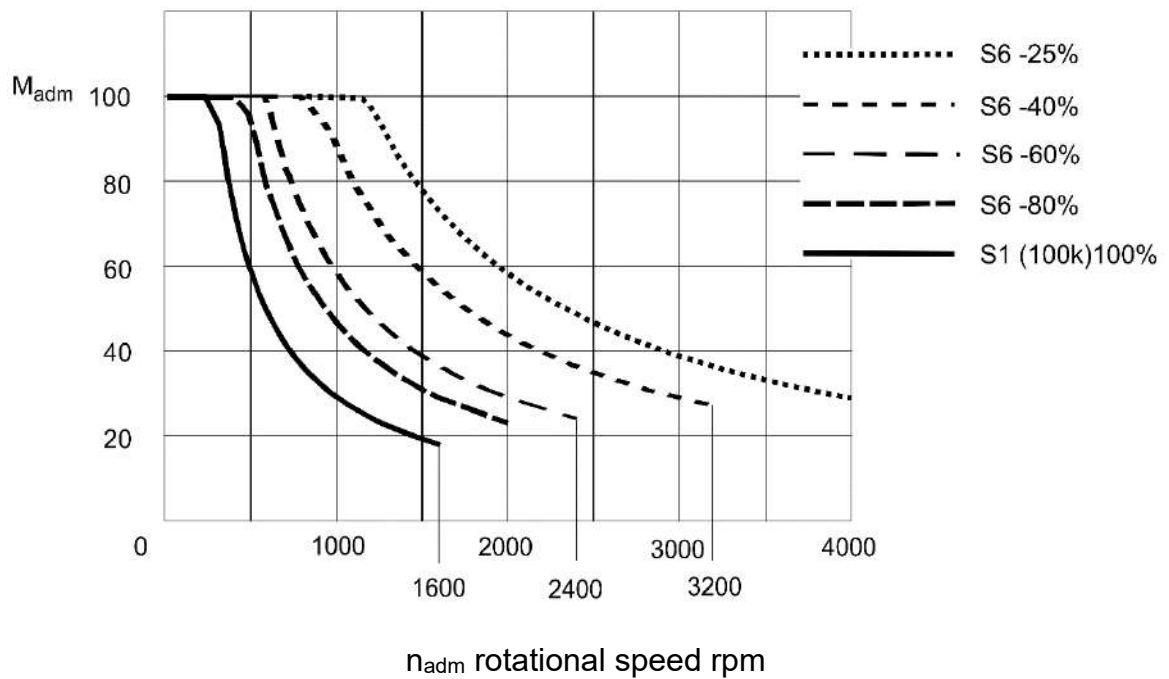
**Performance Data Tool Drive  
(Grease lubricated)**

**4xx.x25-TI02-zh**

**Power [kW]**



**Torque [Nm]**



The data for duty cycle are valid for 10 min.

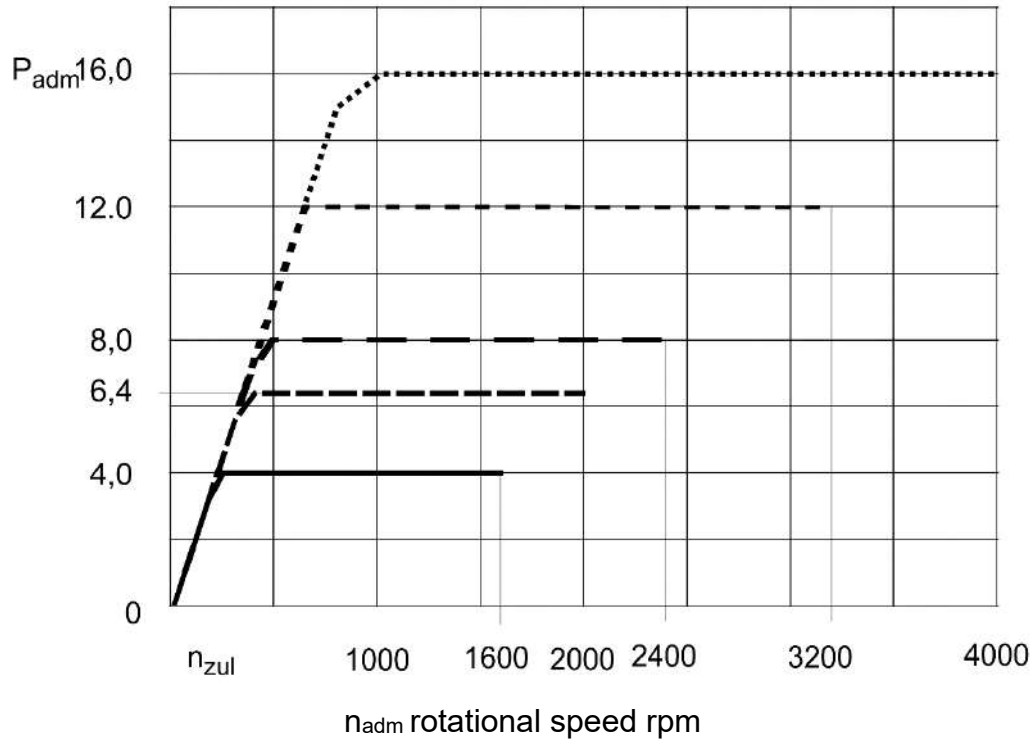
technical changes reserved

**Technical Data**

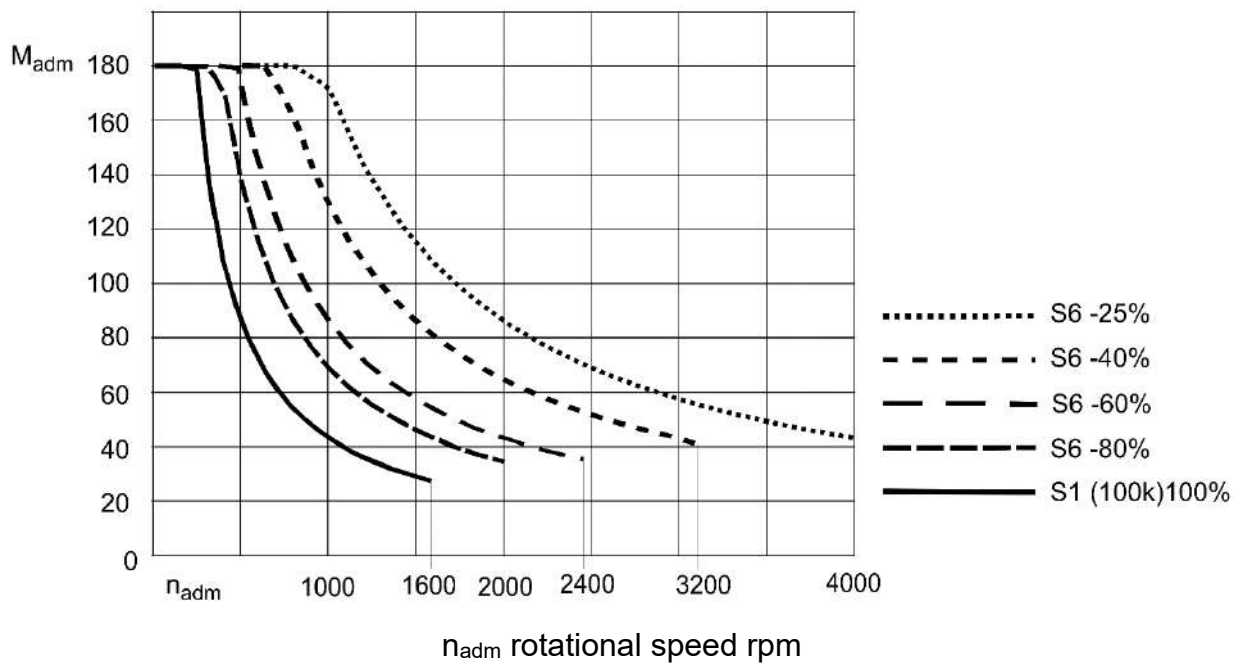
**Performance Data Tool Drive  
(Grease lubricated)**

**4xx.x32-TI02-zh**

**Power [kW]**



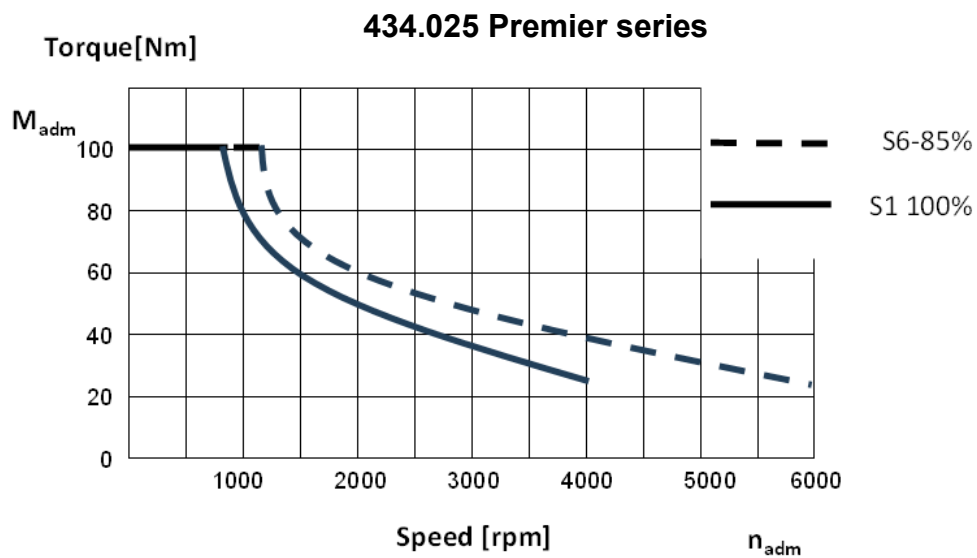
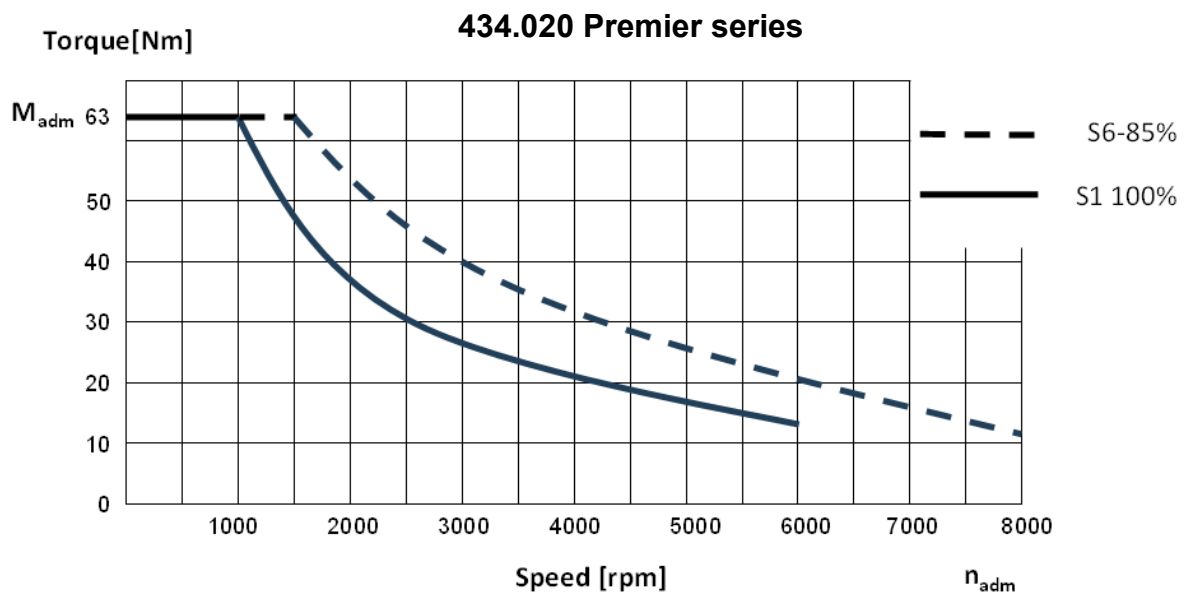
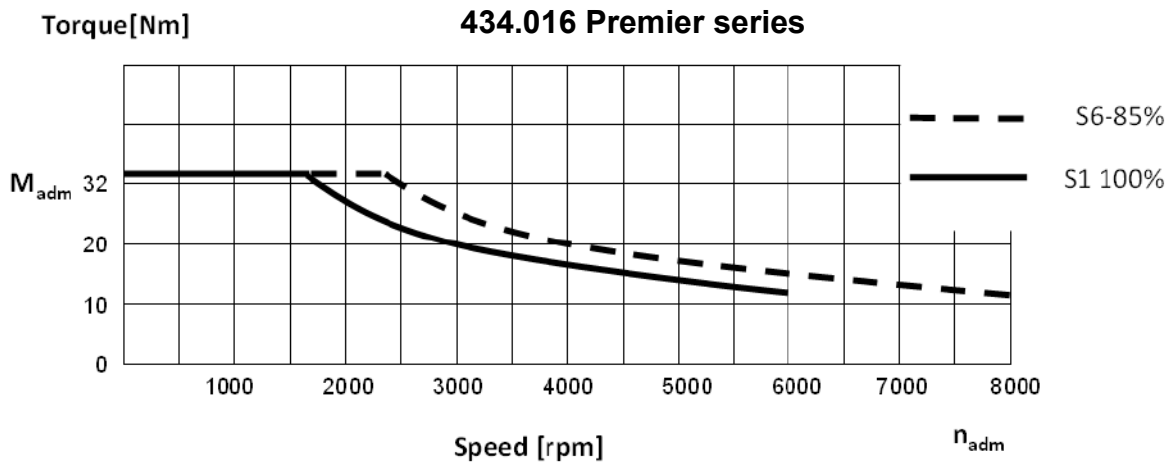
**Torque [Nm]**



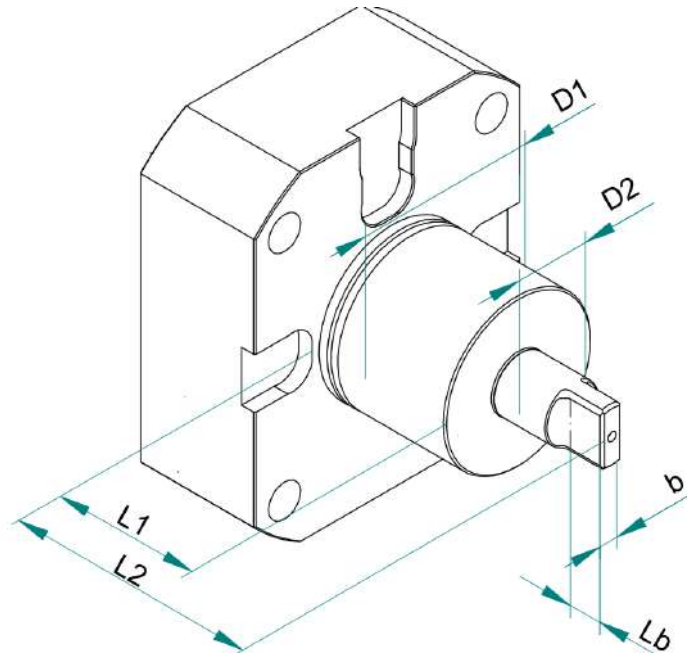
The data for duty cycle are valid for 10 min.

technical changes reserved

## Performance data of tool drive for 434.0xx Premier Series



## Dimensions for BMT tooling interface :



Tooling for interface	control measures [mm]							
	D1	D2	D3	b	L1	L2	L3	Lb
<b>BMT 45</b>	44,9 <sub>-0,05</sub>	35	23	6 <sub>-0,02</sub>	40	60	84 <sub>-0,3</sub>	8
<b>BMT 55</b>	54,9 <sub>-0,05</sub>	40	29	8 <sub>-0,02</sub>	30	75	104 <sub>-0,3</sub>	10
<b>BMT 55 short</b>	54,9 <sub>-0,05</sub>	40	29	8 <sub>-0,02</sub>	30	54	83 <sub>-0,3</sub>	10
<b>BMT 65</b>	64,9 <sub>-0,05</sub>	45	29	10 <sub>-0,02</sub>	32	81	112 <sub>-0,3</sub>	14
<b>BMT 65 short</b>	64,9 <sub>-0,05</sub>	45	29	10 <sub>-0,02</sub>	44	72	91 <sub>-0,3</sub>	14
<b>BMT 75</b>	74,9 <sub>-0,05</sub>	55	38	14 <sub>-0,02</sub>	43	80	110 <sub>-0,3</sub>	15
<b>BMT 85</b>	84,9 <sub>-0,05</sub>	65	30	16 <sub>-0,02</sub>	48	100	140 <sub>-0,3</sub>	20